

Determinant

COMPRESSED VERSION

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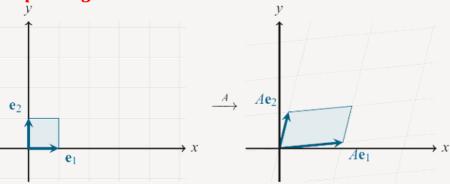


Geometric interpretation

☐ The volume is a n-alternating multilinear map on all n-parallelepipeds such that the volume of standard unit parallelepiped is one.

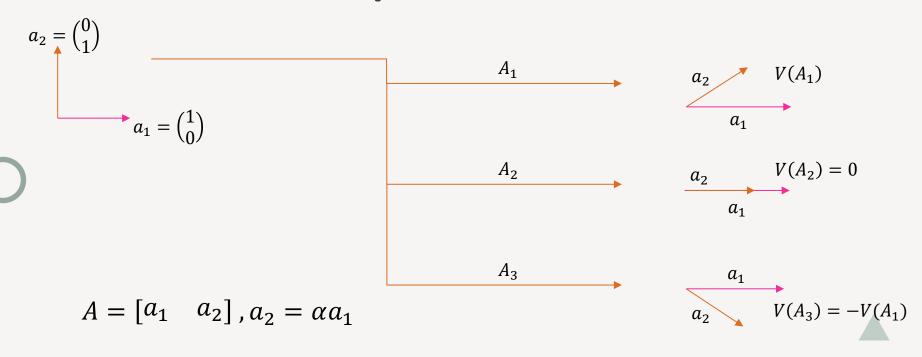
volume of output region

volume of input region



A 2×2 matrix A stretches the unit square (with sides e_1 and e_2) into a parallelogram with sides Ae_1 and Ae_2 (the columns of A). The determinant of A is the area of this parallelogram.

Geometric interpretation

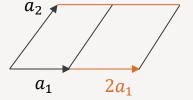


CE282: Linear Algebra

 $V(a_1, a_2) = -V(a_2, a_1)$

Volume Example

- 2D Case
 - \circ $V(a_1, a_2)$
 - \circ V(2 a_1, a_2) = 2V(a_1, a_2)
 - \circ $V(-a_1, a_2) = -V(a_1, a_2)$
 - $\circ \quad \forall (\beta a_2, a_1) = -\beta \ \forall (a_1, a_2)$





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Bilinear Form over a complex vector

Definition

Suppose V and W are vector spaces over the same field \mathbb{C} . Then a function α : V

 $\times W \to \mathbb{C}$ is called a bilinear form if it satisfies the following properties:

It is linear in its first argument:

$$\alpha(\mathbf{v_1} + \mathbf{v_2}, \mathbf{w}) = \alpha(\mathbf{v_1}, \mathbf{w}) + \alpha(\mathbf{v_2}, \mathbf{w})$$
 and

$$\alpha(\lambda \mathbf{v_1}, \mathbf{w}) = \lambda \alpha(\mathbf{v_1}, \mathbf{w})$$
 for all $\lambda \in \mathbb{C}, \mathbf{v_1}, \mathbf{v_2} \in V$, and $\mathbf{w} \in W$.

It is conjugate linear in its second argument:

$$\alpha (v, w_1 + w_2) = \alpha(v, w_1) + \alpha(v, w_2)$$
 and

$$\alpha(\mathbf{v}, \lambda \mathbf{w_1}) = \overline{\lambda}\alpha(\mathbf{v}, \mathbf{w_1})$$
 for all $\lambda \in \mathbb{C}, \mathbf{v} \in V$, and $\mathbf{w_1}, \mathbf{w_2} \in W$.

The set of bilinear forms on v is denoted by v^2 .



Alternating bilinear form

Definition

A bilinear form $\alpha \in V^{(2)}$ is called alternating if

$$\alpha(v,v)=0$$





Multilinear Forms

Definition

Suppose $\mathcal{V}_1, \mathcal{V}_2, ..., \mathcal{V}_p$ are vector spaces over the same field \mathbb{F} . A function

$$f: \mathcal{V}_1 \times \mathcal{V}_2 \times \cdots \times \mathcal{V}_p \to \mathbb{F}$$

is called a multilinear form (f \in V^(p)) if, for each $1 \leq j \leq p$ and each $v_1 \in \mathcal{V}_1, v_2 \in \mathcal{V}_2, \dots, v_p \in \mathcal{V}_p$, it is the case that the function $g: \mathcal{V}_j \to \mathbb{F}$ defined by

$$g(\mathbf{v}) = f(\mathbf{v}_1, \dots, \mathbf{v}_{j-1}, \mathbf{v}, \mathbf{v}_{j+1}, \dots, \mathbf{v}_p) \qquad \text{for all } \mathbf{v} \in \mathcal{V}_j$$

is a linear form.





Multilinear Forms

Definition

Suppose m is a positive integer.

- An m-linear form α on V is called **alternating** if $\alpha(v_1, ..., v_m) = 0$ whenever $v_1, ..., v_m$ is a list of vectors in V with $v_j = v_k$ for some two distinct values of j and k in $\{1, ..., m\}$.
- $V_{alt}^{(m)} = \{ \alpha \in V^{(m)} : \alpha \text{ is an alternating } m\text{-linear form on } V \}.$



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Alternating multilinear forms and linear dependence

Theorem

Suppose m is a positive integer and lpha is an alternating m-linear form on

V. If v_1, \dots, v_m is a linearly dependent list in V, then

$$\alpha(v_1, \dots, v_m) = 0$$

Proof



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Swapping input vectors in an alternating multilinear form

Theorem

Suppose m is a positive integer, α is an alternating m-linear form on V, and $v_1, ..., v_m$ is a list of vectors in V. Then swapping the vectors in any switch of $\alpha(v_1, ..., v_m)$ changes the value of α by a factor of -1.

Okey, clearing up the last detail. Suppose we know that $A(e_1, e_2, e_3, e_4, e_5) = 7$. What should $A(e_3, e_5, e_1, e_2, e_4)$ be?

$$A(e_3, e_5, e_1, e_2, e_4) = -A(e_3, e_4, e_1, e_2, e_5)$$

$$= A(e_3, e_2, e_1, e_4, e_5)$$

$$= -A(e_1, e_2, e_3, e_4, e_5) = -7$$

What if we did the switching in a different order? Would we get the same sign? It turns out that, yes, we would!



Example

What we need to show is that there is a way to assign a sign to every permutation of $\{1, 2, 3, ..., k\}$ such that, switching the order of any two elements, switches the sign. For example:

$$(1,2,3) \rightsquigarrow 1 \qquad (1,3,2) \rightsquigarrow -1$$

$$(2,1,3) \leadsto -1 \qquad (2,3,1) \leadsto 1$$

$$(3,1,2) \rightsquigarrow 1 \qquad (3,2,1) \rightsquigarrow -1$$

Here is the rule: The sign of $(\sigma(1), \sigma(2), \ldots, \sigma(k))$ is

$$(-1)^{\#\{(i,j): i < j \text{ and } \sigma(i) > \sigma(j)\}}$$
.

$$A(e_{j_1}, e_{j_2}, \dots, e_{j_k}) = \operatorname{sign}(\sigma) A(e_{j_{\sigma(1)}}, e_{j_{\sigma(2)}}, \dots, e_{j_{\sigma(k)}}).$$



Definition

- In **Theorem (9)** if we consider $\alpha(e_1,...,e_n)=1$, then we can say that determinant is a multilinear alternating form (volume of the transformed vectors.)
- Determinant is defined for square matrices.

Definition

Suppose that n is a positive integer and A is an n-by-n square matrix. Then:

$$detA = \sum_{(j_1,\dots,j_n)\in perm(n)} (sign(j_1,\dots,j_n)) A_{j_1,1} \dots A_{j_n,n}$$



Definition

Note

Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be the linear transformation determined by a 2 \times 2 matrix A. If S is a parallelogram in \mathbb{R}^2 , then $\{area\ of\ T(S)\} = |\det A|.\{area\ of\ S\}$

If T is determined by a 3 \times 3 matrix A, and if S is a parallelepiped in \mathbb{R}^3 , then

 $\{volume\ of\ T(S)\} = |\det A|.\{volume\ of\ S\}$

Example

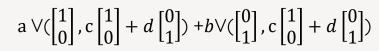
Example

Determinant of 2*2 matrix

Determinant of 3*3 matrix

$$\bigvee \begin{pmatrix} \begin{bmatrix} a & c \\ b & d \end{bmatrix} \end{pmatrix} = \bigvee \begin{pmatrix} \begin{bmatrix} a \\ b \end{bmatrix}, \begin{bmatrix} c \\ d \end{pmatrix} \end{pmatrix}$$

$$\forall (a \begin{bmatrix} 1 \\ 0 \end{bmatrix} + b \begin{bmatrix} 0 \\ 1 \end{bmatrix}, c \begin{bmatrix} 1 \\ 0 \end{bmatrix} + d \begin{bmatrix} 0 \\ 1 \end{bmatrix})$$



$$\operatorname{ac} \vee (\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix}) + \operatorname{ad} \vee (\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}) + \operatorname{bc} \vee (\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}) + \operatorname{bd} \vee (\begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix}) + \operatorname{0} + \operatorname{ad} \vee (\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}) + \operatorname{bc} \vee (\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}) + \operatorname{0} + \operatorname{0$$

$$=ad - bc \lor (\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}) = ad - bc$$

$$\Rightarrow \bigvee \begin{bmatrix} a & c \\ b & d \end{bmatrix} \Rightarrow ad - bc$$

Famous Formula of Determinant



Determinant

Example

Let $n = \dim V$.

- If I is the identity operator on V, then $\alpha_1=\alpha$ for all $\alpha\in V_{alt}^{(n)}$. Thus, $\det I=1$.
- More generally, if $\lambda \in F$, then $\alpha_{\lambda I} = \lambda^n \alpha$ for all $\alpha \in V_{alt}^{(n)}$. Thus, $\det(\lambda I) = \lambda^n$.
- Still more generally, if $T \in \mathcal{L}(V)$ and $\lambda \in \mathbf{F}$, then $\alpha_{\lambda T} = \lambda^n \alpha_T = \lambda^n (\det T) \alpha$ for all $\alpha \in V_{alt}^{(n)}$. Thus, $\det(\lambda T) = \lambda^n \det T$.



Gaussian Elimination & Determinant

Note

- ■Row operations
 - \square Let A be a square matrix.
 - \square If a multiple of one row of A is added to another row to produce a matrix B, then det(B) = det(A)
 - \square If two rows of A are interchanged to produce B, then $\det(B) = -\det(A)$
 - \square If one row of A is multiplied by k to produce B, then $\det(B) = k \cdot \det(A)$

(1) If one row or column is zero, then determinant is zero

$$\begin{vmatrix} 0 & 0 & 0 \\ a & b & c \\ d & e & f \end{vmatrix} = 0$$

Determinant of zero matrix is...

$$\det(A) = \sum_{j=1}^{n} (-1)^{1+j} a_{1j} \det(A_{1j})$$
$$\det(A) = \sum_{\sigma \in S_n} \operatorname{sgn}(\sigma) \prod_{i=1}^{n} a_{i\sigma(i)}$$



(2) If two rows or columns of matrix are same, then determinant is zero.

$$A = \begin{bmatrix} 1 & -2 & 3 \\ 1 & -2 & 3 \\ 5 & 3 & -1 \end{bmatrix}$$





- ☐ (3) If two rows or columns of matrix are interchanged, the sign of determinant is changes!





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- □ (5) Row and Column Operations
 - If a multiple of one row/column of A is added to another row/column to produce a matrix B, then det(A) = det(B).

Proof?

Example

$$\begin{vmatrix} 1 & -1 & 2 \\ 0 & 2 & -3 \\ 0 & 0 & -2 \end{vmatrix} = \begin{vmatrix} 1 & -1 & 2 \\ 1 & 1 & -1 \\ 1 & -1 & 0 \end{vmatrix} = \begin{vmatrix} 1 & -1 & 6 \\ 1 & 1 & 3 \\ 1 & -1 & 4 \end{vmatrix}$$

(6) If A is a triangular matrix, then det(A) is the product of the entries on the main diagonal of A.



$$\begin{vmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{vmatrix} = abc \qquad \begin{vmatrix} a & 0 & 0 \\ d & b & 0 \\ e & f & c \end{vmatrix} = abc$$

- Determinant of identity matrix is...
- U is unitary, so that $|\det(U)|=I$



 (7) If a column or row is multiply to k then determinant is multiply to k.

$$\begin{vmatrix} ka_{11} & \dots & ka_{1n} \\ \vdots & \ddots & \vdots \\ a_{n1} & \dots & a_{nn} \end{vmatrix} = k \begin{vmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{n1} & \dots & a_{nn} \end{vmatrix}$$



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■ (8) If a row/column is multiple of another row/column then determinant is





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- (9) If columns/rows of matrix are linear dependent then its determinant is zero
- (10) If columns/rows of matrix are linear dependent if and only if its determinant is zero.
- □ (11) Transposing a matrix does not change the determinant.



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Reference

- Chapter 3: Linear Algebra and Its Applications, David C. Lay.
- □ Chapter 9: Part B and C: Linear Algebra Done Right, Sheldon Axler.





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